

FIG. 1

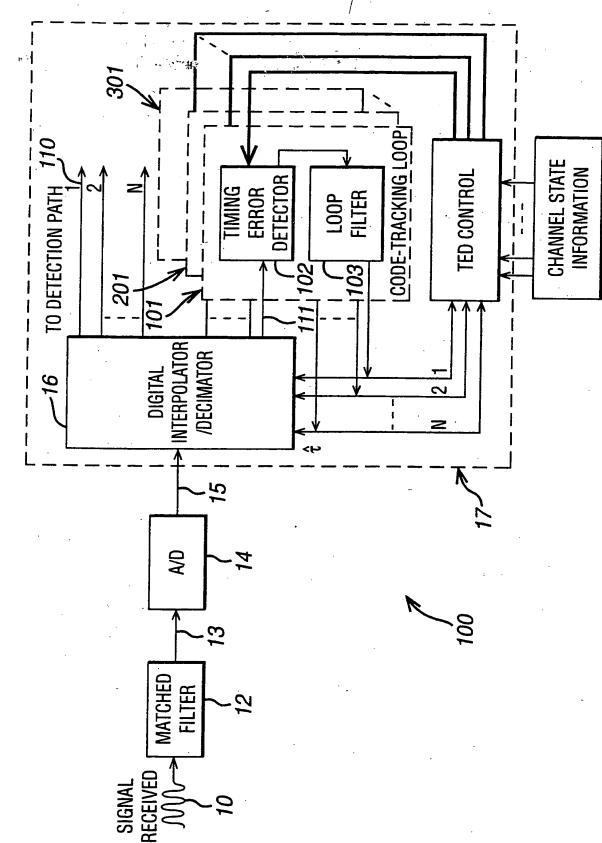
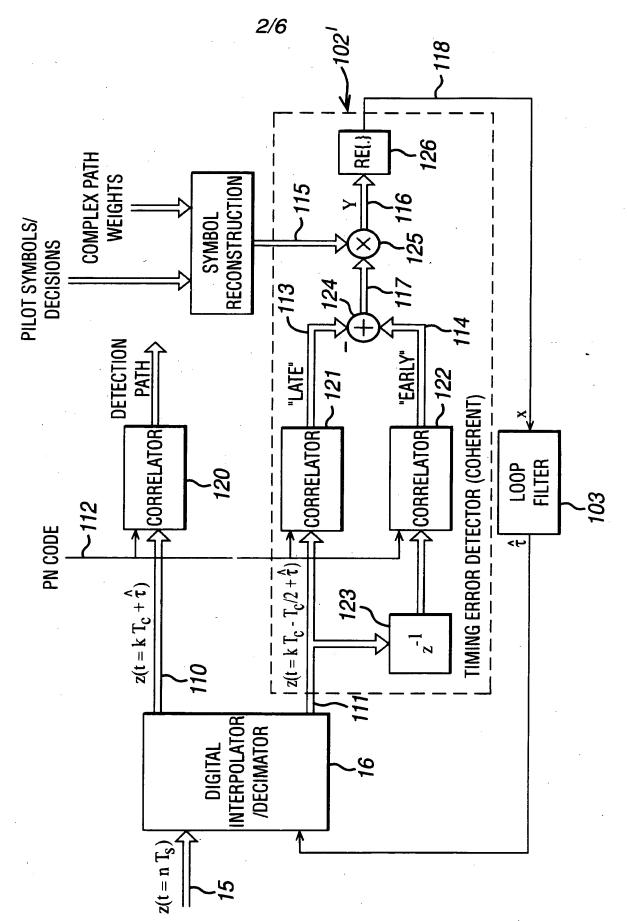


FIG. 2

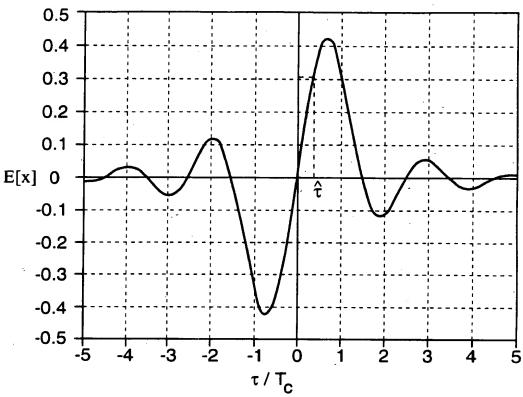


3/6 102 132 RE{.} path  $j = 1, 2, ..., N, j \neq i$ DELAYS PATH INTERFERENCE COMPUTATION 118 CANCELLATION INTERFERENCE 116 | 130\_\_ COMPLEX PATH WEIGHTS 173 -115 RECONSTRUCTED 125 **SYMBOLS** PILOT SYMBOLS/ DECISIONS path i 115 124 "EARLY" -122 "LATE" 113 **PATH** DETECTION ≀× CORRELATOR! **以CORRELATOR** 少CORRELATOR -121 FILTER L00P 103 ~112  $z(t=k\;T_C^{\phantom{0}}+T_C/2+{\stackrel{\wedge}{\tau}})$ PN CODE -123  $\int z(t = k T_c - T_c/2 + t^2)$  $z(t=k T_c + \overset{\wedge}{\tau})$ INTERPOLATOR /DECIMATOR DIGITAL 16  $z(t = n T_s)$ 

FIG. 3

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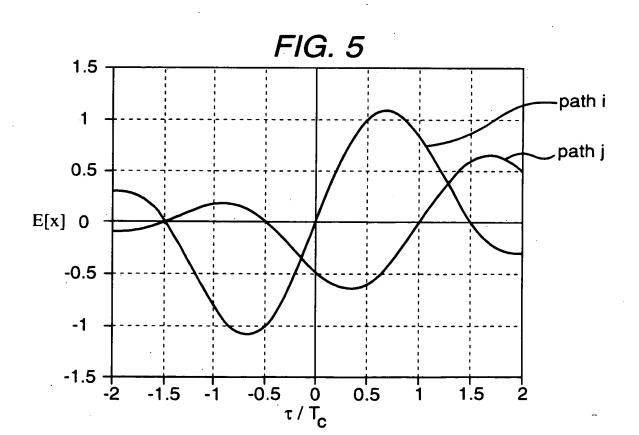


FIG. 6

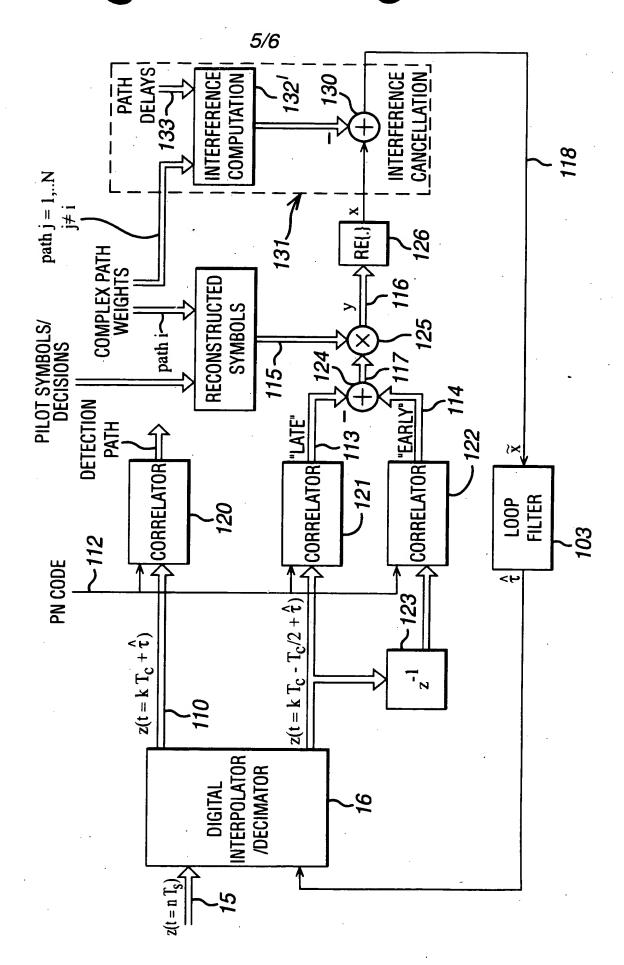


FIG. 7

